#### Standard driver card

## **CB-016N6·BN6**

RoHS CE Conformity Conformity

#### $\cdot$ [Applicable MDR models] $\lnot$

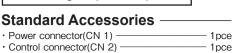
PM486FE·PM500FE PM486FP·PM500FP PM570FE·PM605FE



# CB-016N6-LT

blank : UL non-applicable
UL : UL applicable

- LT : Low temp N : For standard motor
- NPN signal input and output
- P : For standard motor PNP signal input and output
- BN : For built-in brake motor
- NPN signal input and output
- BP : For built-in brake motor PNP signal input and output



Mounting screws and nuts Screw M4×15



## ■ Acceleration and deceleration time is adjustable.

Speed can be set for  $0\sim2.5$  sec with the VR on the driver card.

This reduces impact at starting/stopping Power Moller.

#### ■ Speed can be set in 20 steps

Digital setting method makes easy speed adjustment for each driver card

#### Stable speed function

2pcs 2pcs

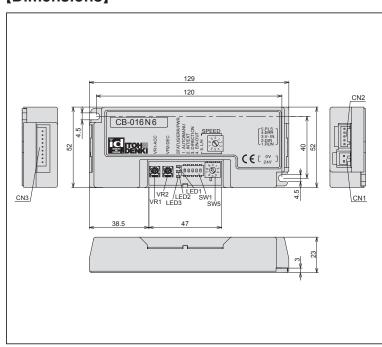
Transfer speed is kept stable regardless of the load variation.

It helps improve transfer accuracy.

#### **■** Error types and history can be checked

LED can display thermal error / lock error / low voltage error, as well as error generation history.

#### (Dimensions)



#### Dip switch (SW1)

| SW1#1 | Selection of manual or automatic thermal device recovery |
|-------|--|
| SW1#2 | Selection of internal or external speed change           |
| SW1#3 | Selection of motor turning direction; CW or CCW          |
| SW1#4 | Selection of error signal discharge mode                 |
| SW1#5 | Speed range setting                                      |

#### Connector (CN)

| CN 1 | Power connector (2P)                       |
|------|--|
| CN 2 | Control connector (5P)                     |
| CN 3 | Motorr connector (9P)<10P for brake motor> |

#### Potentiometer (VR)

| VP2 Decoloration from Stop signal | VR1 | Acceleration from Run signal  |
|-----------------------------------|-----|-------------------------------|
| VHZ Deceleration from Stop Signal | VR2 | Deceleration from Stop signal |

#### LED

| 1 | Powered and functions normally  |
|---|---|
| 2 | Indicates type of error   |
| 3 | Indicates number of error occurrence from thermister reaction, motor stall or under voltage |

#### Rotary switch(SW5)

Speed change in 20 steps by combining with SW1#5.

Driver Card CB-016

**(Error History)** 

If thermister, motor stall or under voltage error arises while

the power Moller is running, the error status and frequency of error occurrence are identified by LED 2 and LED 3.

stall error

under voltage error

Error occurred at first time

Error occurred at third time (same error in series)

Error occurred at second time (same error as the first one)

Error occurred at second time (different error as from the first one) Error occurred at third time (same error as the first or second one)

thermister error

blinks at

blinks at

Illuminates

blinks at

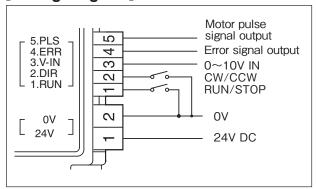
1Hz

blinks at

6Hz

Illuminates

### [Wiring diagram]



- \*Wiring should be made while the product is not powered.
- \*Switch for Run/stop or CW/CCW is an option and is not supplied.
- \*Relay contact or PLC output can be used instead of the above switch.

## (Specitications)

| (Specitications)             |   |   | Direction Setting   |            |                    |                         |   |   |  |
|------------------------------|---|---|---|------------|--------------------|-------------------------|---|---|--|
| Power vo                     | Itage   | 24V DC±10%  | Reverse direction by external DIR signal can be permitted even while motor is running   |            |                    |                         |   |   |  |
| Rated vo                     | Itage   | 24V DC  | Power Moller turning direction can be set or changed either internally by integral dip switch or externally by optional switch. |            |                    |                         |   |   |  |
| Static cu                    | rrent   | 0.03A   | 9   | etting f   | for Turning I      | Direction In ca         | se of use of CB-                                |   |  |
| Starting of                  | current   | 4.0A  |   |            |                    | SW                      | 1 # 3   |   |  |
| Wiring Power connector       |   | 0.5~1.5mm² (AWG:20~14)  |   |            |                    |                         | ON 88 88  | OFF                                     |  |
|                              | ontrol connector                                  | 0.08~0.5mm² (AWG:28~20)   |   |            | ERR 4              | <u> </u>                |   |   |  |
| Motor starts ru              | nning from RUN signal                             | ≦15msec   |   |            | ERR V-IN DIR RUN   | Open contact            | cw +(Q)*  | ccw ((Q)),                              |  |
| Protections                  |   | Integral 6.3A fuse (+ side) Diode against miss-wiring   |   | FE<br>type |                    |                         |   |   |  |
| Thermister                   |   | 95°C on PCB or 105°C in motor   |   |            | ERR 7-IN 60 RUN 1  | cw/ccw                  | ccw ( C)  | cw 🔊                                    |  |
| Current limiting             |   | 4A  |   |            |                    | Close contact           | <i>ISO</i>                                      | (CC)                                    |  |
| Ambient temperature          |   | O to +40°C $\langle ^{**1} LT$ (Low temperature) option is -30 to 10°C. $\rangle$   |   |            | ERR V-IN DIR RUN 1 | <b>'</b> \ \            |   |   |  |
| Relative humidity Atmosphere |   | ≦90%RH(no condensation)   |   | FP         | DIR RUN 2          | Open contact            | ccw (Q)   | cw +(C),                                |  |
|                              |   | No corrosive gas  |   | type       | ERR 6              |                         |   |   |  |
| Vibration                    |   | ≦0.5G   |   |            | V-IN CO            | CW/CCW<br>Close contact | cw +(@)+  | ccw ((((((((((((((((((((((((((((((((((( |  |
| Installatio                  | on  | Indoor □ □ □ □ □ □ □ □ □ □ □ □ □ □ □ □ □ □  |   | <u> </u>   |                    |                         |   |   |  |
| Turning o                    | Irection  | Can be set with DIP SW1#3.  | *Turning direction viewed from the Power Moller's power cable side  |            |                    |                         |   |   |  |
| Error signal                 |   | Generated by thermal cutoff / Power Moller stall / low power supply voltage / connector disconnection / fuse blow-off.  SW1-4 allows the selection of the error signal discharge timing: discharge on normal status or dilscharge when error arises.  Error signal is NPN open collector in cace of CB-016N6/BN6.  **Recovery from thermal cutoff error and low voltage error can be selected by DIP SW1#1 for manual recovery (0N) or auto recovery (0FF). |   |            |                    |                         |   |   |  |
|                              |   | • Enabled by setting DIP SW1#2 to OFF.  |   | · Up to    | 20-step se         | tting is possib         | le by DIP SW1                                   | #5 and SW5.                             |  |
| Speed<br>Variation           | Internal  | ON (External speed change)  OFF (Internal speed change)   |   |            | □ □ □<br>1 2 3     | ON<br>B B ↓<br>4 5 OFF  | 8 0 7 2 3 5 3 4 5 5 5 5 5 5 5 5 5 5 5 5 5 5 5 5 |   |  |
|                              |   | • Enabled by setting DIP SW1#2 ON   |   | • Up to 2  |                    | CNIO                    | ing voltage input (0~                           | 10V DC to CN2-3)                        |  |
|                              | External  | ON (External speed change)  OFF (Internal speed change)   |   |            | 4.ERR<br>3.V-IN    | CN2<br>0~10V D          | OUT OV 24V DC                                   |   |  |
|                              | Acceleration                                      | Integral potentiometer VR 1 allows the acceleration adjustment from 0 to 2.5 seconds.   |   |            |                    |                         |   |   |  |
|                              | Deceleration                                      | Integral potentiometer VR 2 allows the deceleration adjustment from 0 to 2.5 seconds.   |   |            |                    |                         |   |   |  |
| Motor puls                   | Motor pulse signal output 2 pulses/motor rotation |   |   |            |                    |                         |   |   |  |
| LED                          |   | Power (green) Error (red) Frequency (red/oran   | Power (green) Error (red) Frequency (red/orange)  |            |                    |                         |   |   |  |
| Type of b                    | orake   | Dynamic brake (No holding effect. In case holding effect is required, use MDR with built-in brake option (BR) together with CB-016[BN6][BP6].)  |   |            |                    |                         |   |   |  |
| Brake cur                    | rent*2  | 0.2A (CB-016BN6)  |   |            |                    |                         |   |   |  |

<sup>\*1</sup> Driver card with LT option have a limitation of nominal speed and speed setting.

<sup>\*2</sup> Built in brake