

RCM/RFM

Pneumatic Pivot Units | Ordering Information

Base

RCM

RFM

Description

Standard

Integrated Braking

Cylinder

Description

100

100 mm Bore

125

125 mm Bore

160

160 mm Bore

200

200 mm Bore

Opening Angles

100				125, 160, 200			
O	O/LS	V	V/LS	O	O/LS	V	V/LS
N/A				15°			
29°				30°			
45°				43°			
61°				61°			
77°				76°			
92°	N/A	92°		91°	N/A	91°	
104°	N/A	104°		107°	N/A	107°	
121°	N/A	121°		N/A		129°	

Opening angles are easily field adjustable.

Saddle Orientation

Description

O

Horizontal

V

Vertical

O/LS

Inverted Horizontal

V/LS

Inverted Vertical

O

O/LS

V

V/LS



RCM Series

RCM100-O RCM125-O RCM160-O RCM200-O

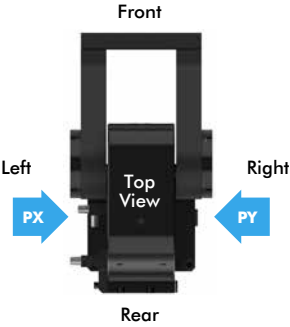
RFM Series

RFM100-V RFM125-V RFM160-V RFM200-V

Ports	Description
N	NPT Ports
G	G Port

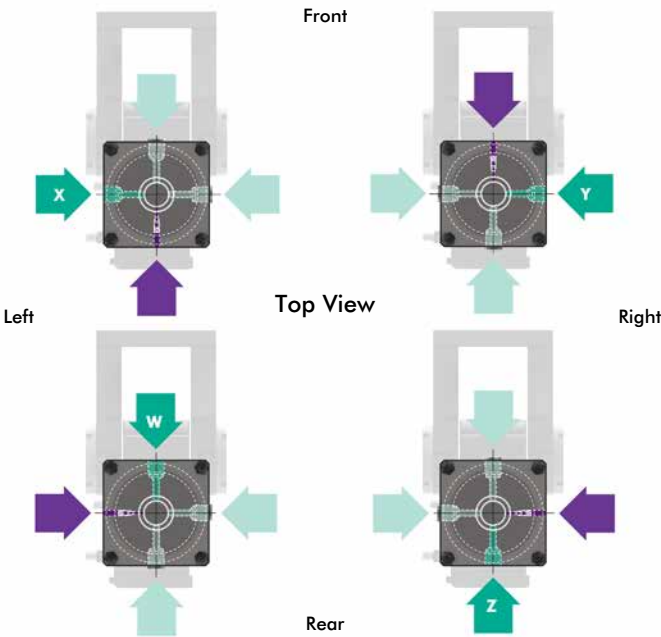
Proximity Switch Type	Description
O	No Proximity Switch
P	Pepperl+Fuchs Proximity Switch
T	Turck Proximity Switch

Proximity Switch Location	Description
P0	No Proximity Switch
PX	Proximity Switch on Left-Side
PY	Proximity Switch on Right-Side



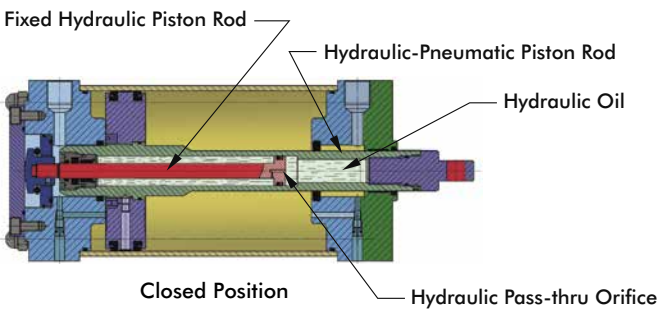
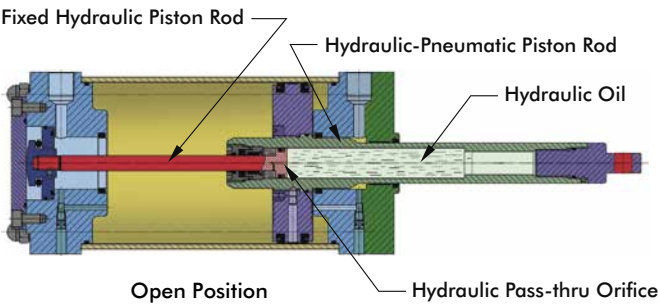
Cylinder Orientation	Description
X	Left-Facing Airport
Y	Right-Facing Airport
W	Front-Facing Airport
Z	Rear-Facing Airport

Air Port
Air Ports Plugged
Cushion Adjustment



Cylinder Operating Principle

The RFM/RCM series pivot units uses a combined pneumatic and hydraulic cylinder, using a hydraulic/pneumatic piston rod within the standard pneumatic cylinder structure. This will allow for standard pneumatic operation while providing shock absorption or dampening in heavy duty applications during opening and closing positioning.

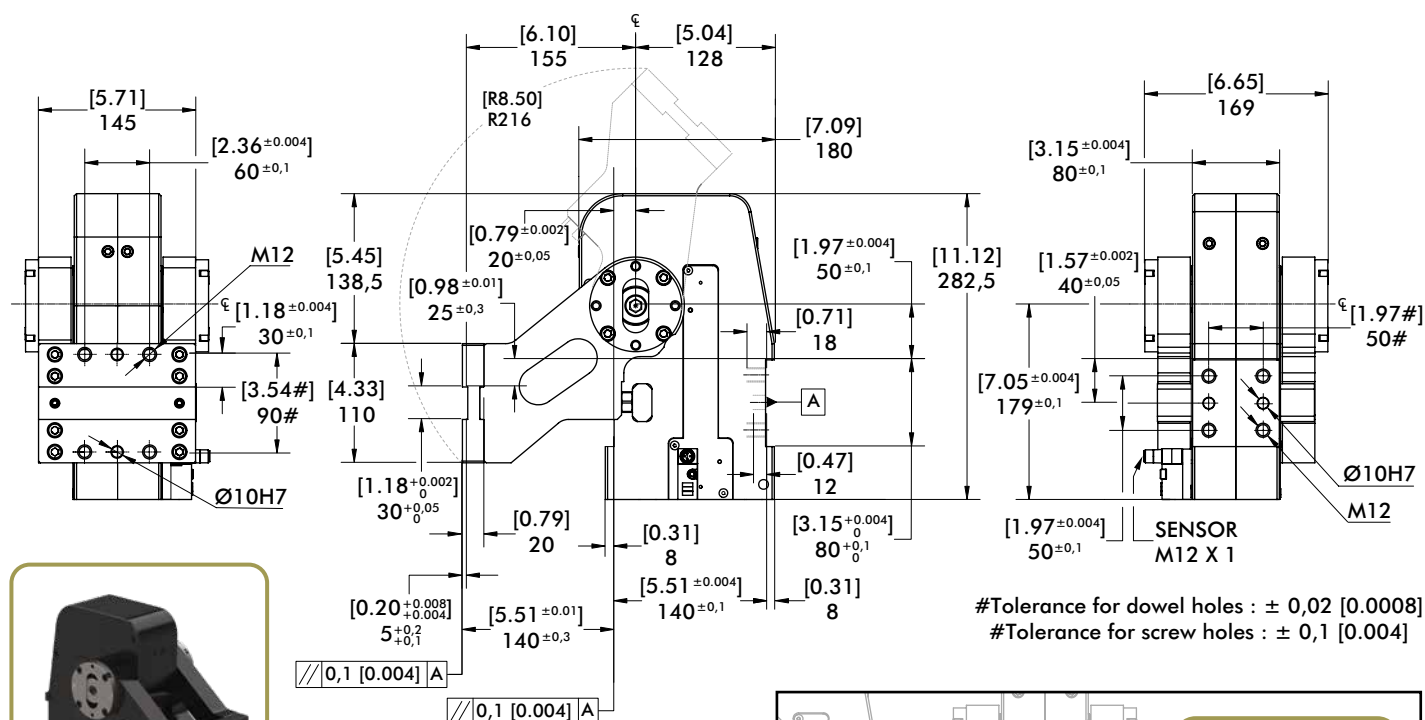


Specifications	Units	100	125	160	200
Max Torque by Load [5 bar] Opening Angle ≤ 92°	Nm [ft-lbs]	150 [111]	240 [171]	410 [302]	660 [487]
Max Torque by Load [5 bar] Opening Angle > 92° / ≤ 121°	Nm [ft-lbs]	110 [81]	180 [133]	300 [221]	480 [354]
Max Torque by Load [5 bar] Opening angle > 121°	Nm [ft-lbs]	55 [41]	65 [48]	100 [74]	175 [129]
Holding Moment	Nm [ft-lbs]	2000 [1475]	3500 [2581]		
RCM Weight	kg [lbs]	~27 [60]	~61 [134]	~74 [163]	~81 [178]
RFM Weight	kg [lbs]	~30 [66]	~64 [141]	~77 [169]	~84 [185]

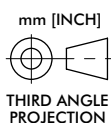
RCM/RFM

Pneumatic Pivot Units | Dimensions

RCM/RFM100 Vertical "V" Orientation Pivot Dimensions



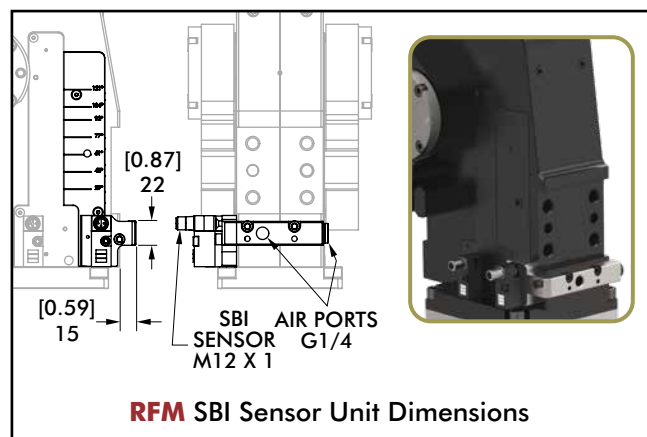
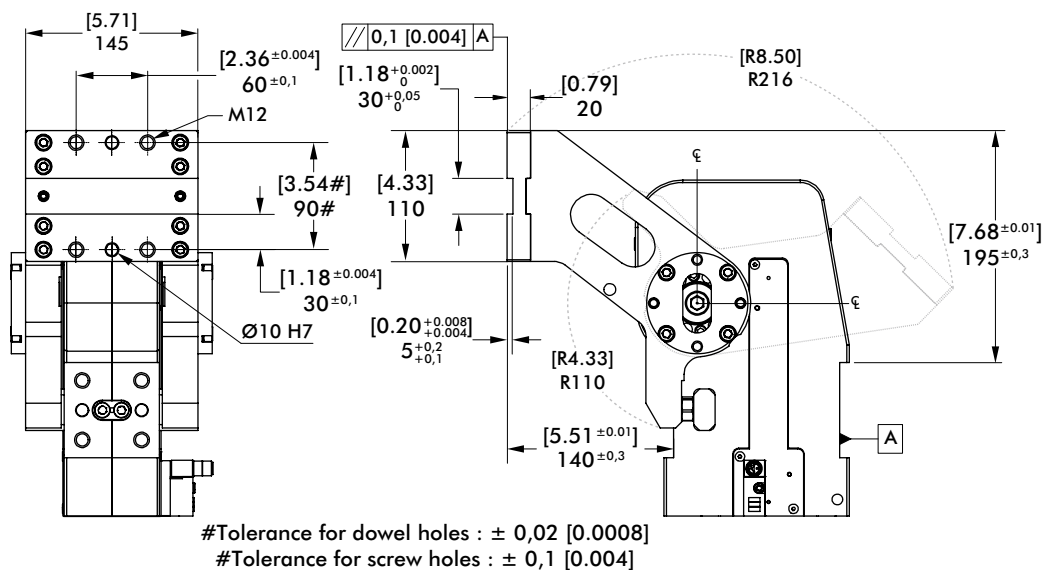
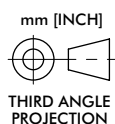
Saddle Arm [26.19 lbs]
Weight: 11.88 Kg



RCM/RFM100 Vertical "V/LS" Orientation Pivot Dimensions



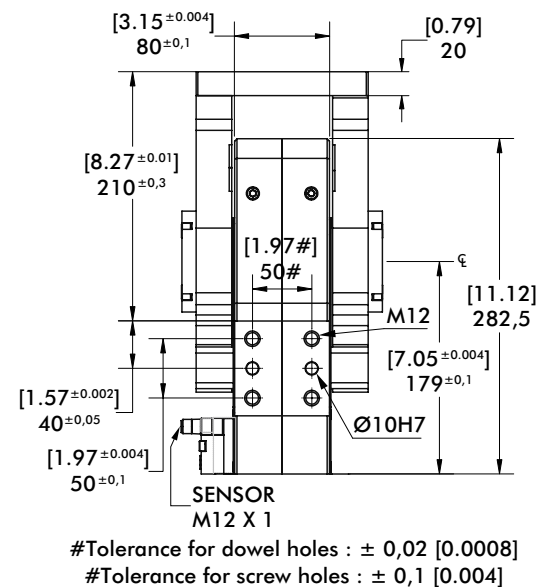
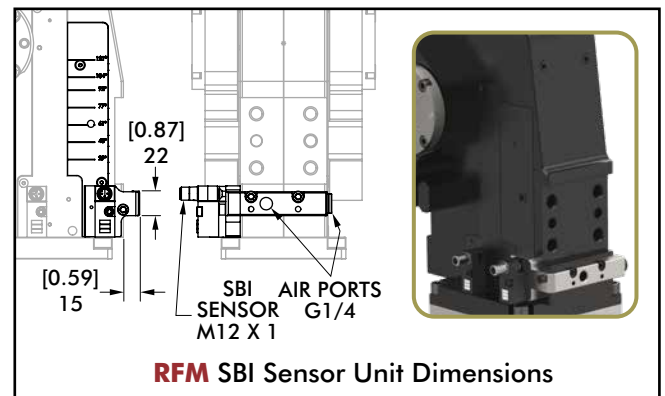
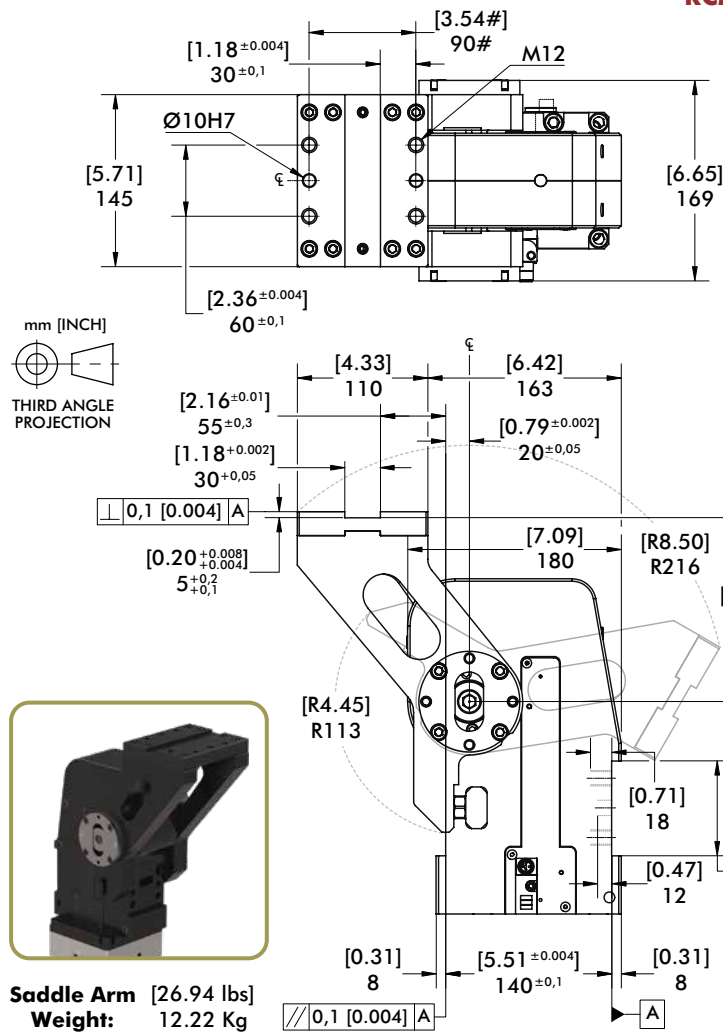
Saddle Arm [27.38 lbs]
Weight: 12.42 Kg



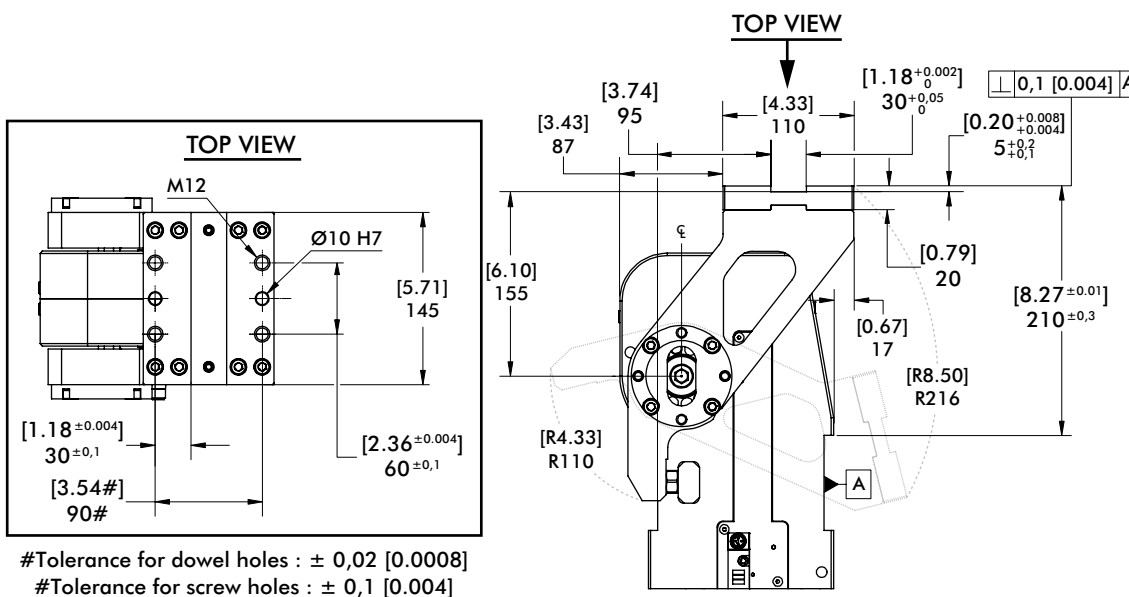
RFM SBI Sensor Unit Dimensions

Pneumatic Pivot Units | Dimensions

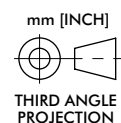
RCM/RFM100 Horizontal "O" Orientation Pivot Dimensions



RCM/RFM100 Horizontal "O/LS" Orientation Pivot Dimensions



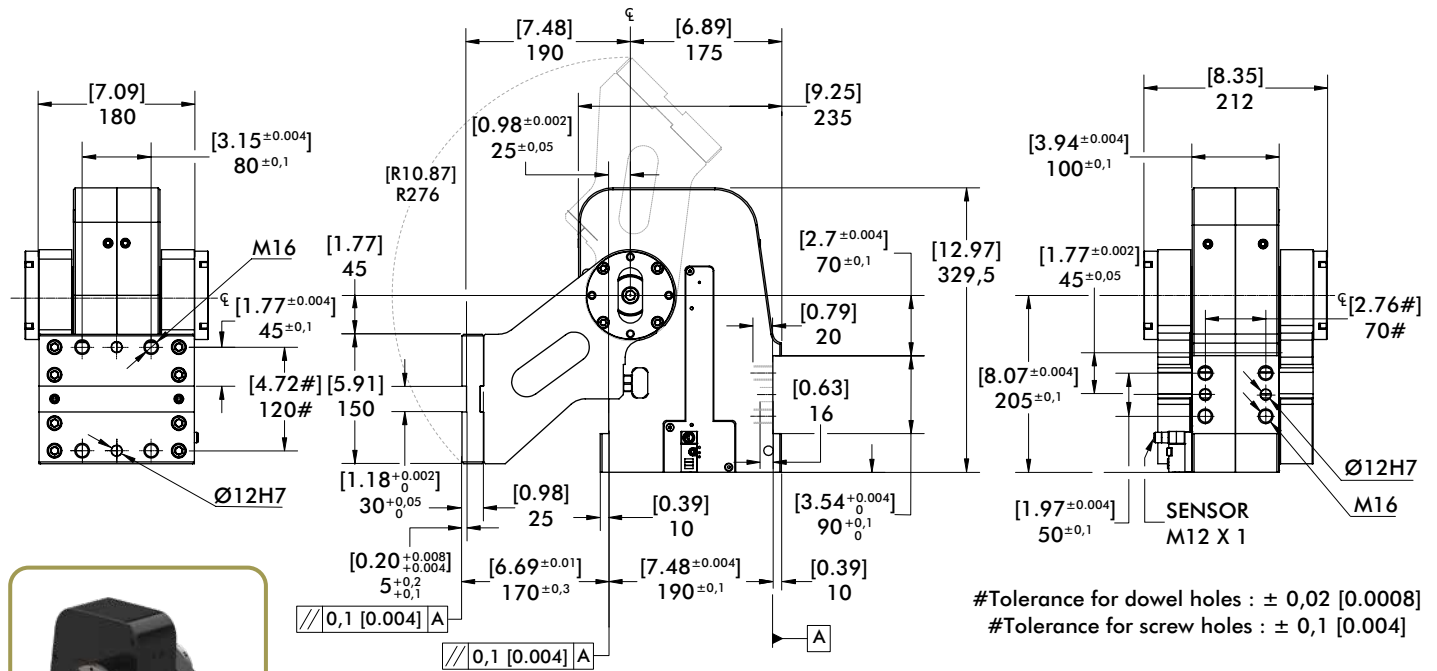
Saddle Arm Weight: [27.69 lbs]
12.56 Kg



RCM/RFM

Pneumatic Pivot Units | Dimensions

RCM/RFM125, 160, 200 Vertical "V" Orientation Pivot Unit and Saddle Dimensions

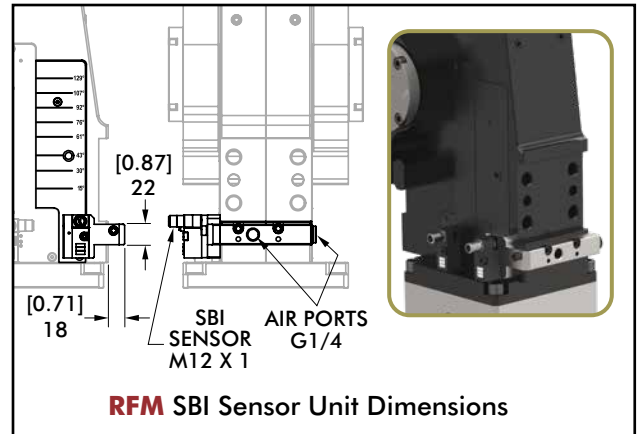
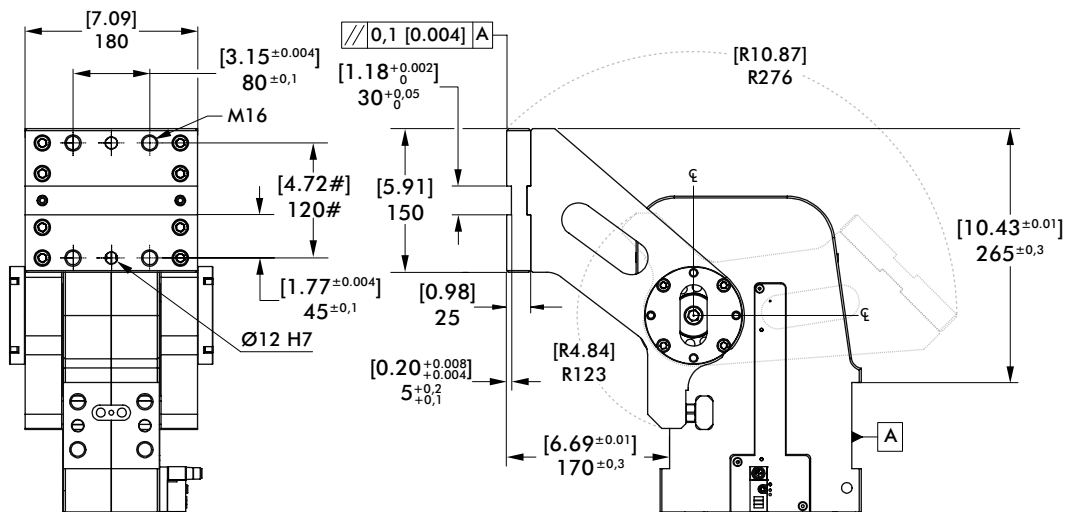
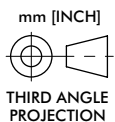


Saddle Arm [52.21 lbs]
Weight: 23.68 Kg

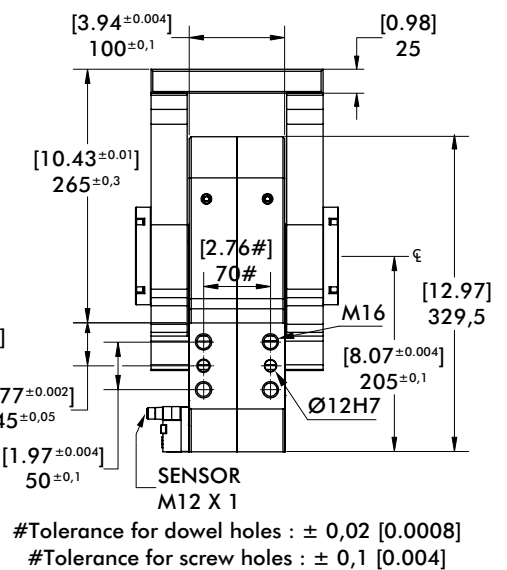
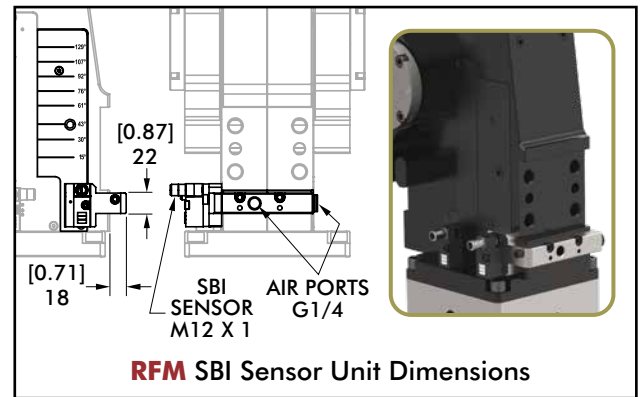
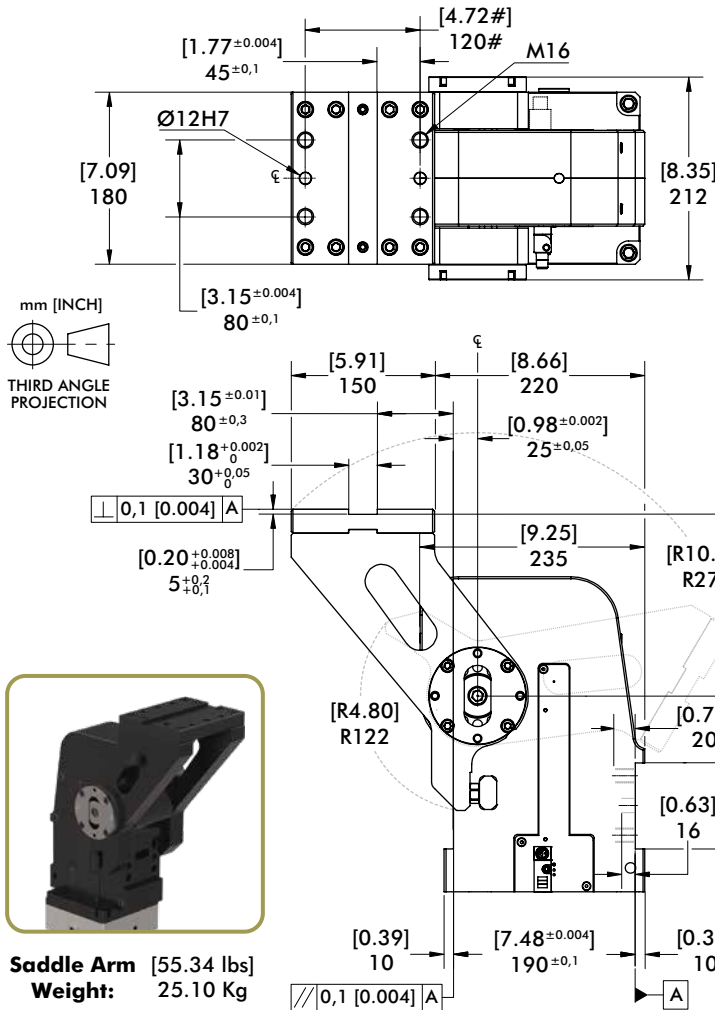
RCM/RFM125, 160, 200 Vertical "V/LS" Orientation Saddle Dimensions



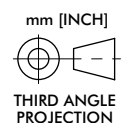
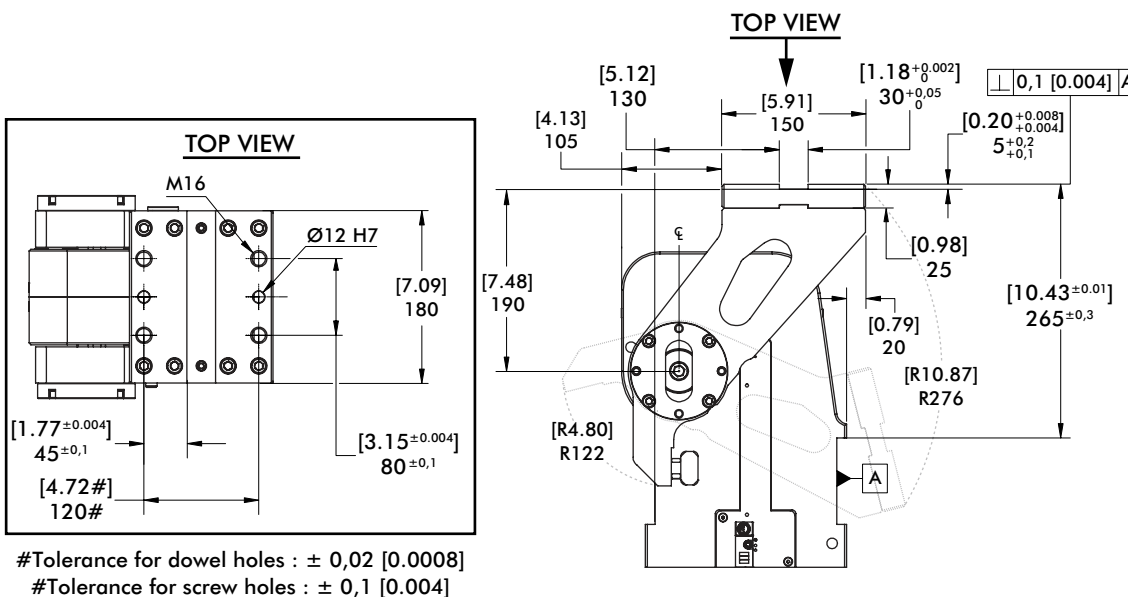
Saddle Arm [55.23 lbs]
Weight: 25.05 Kg

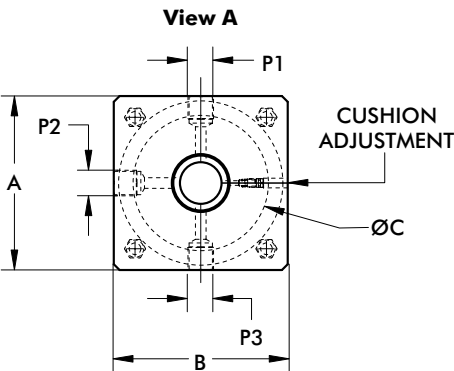
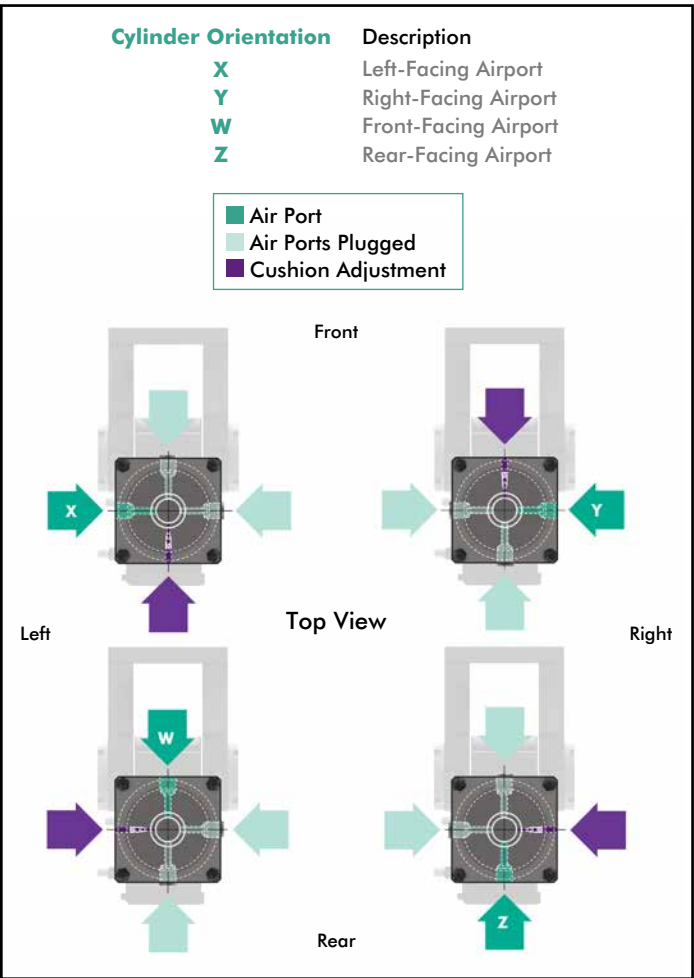
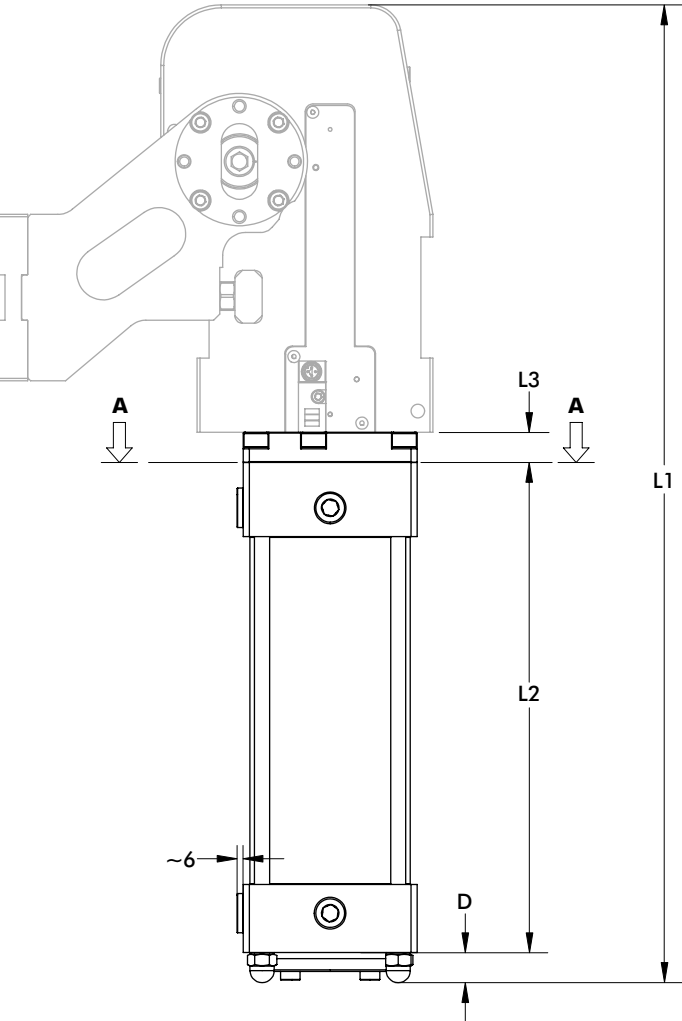


RCM/RFM125, 160, 200 Horizontal "O" Orientation Pivot Unit and Saddle Dimensions



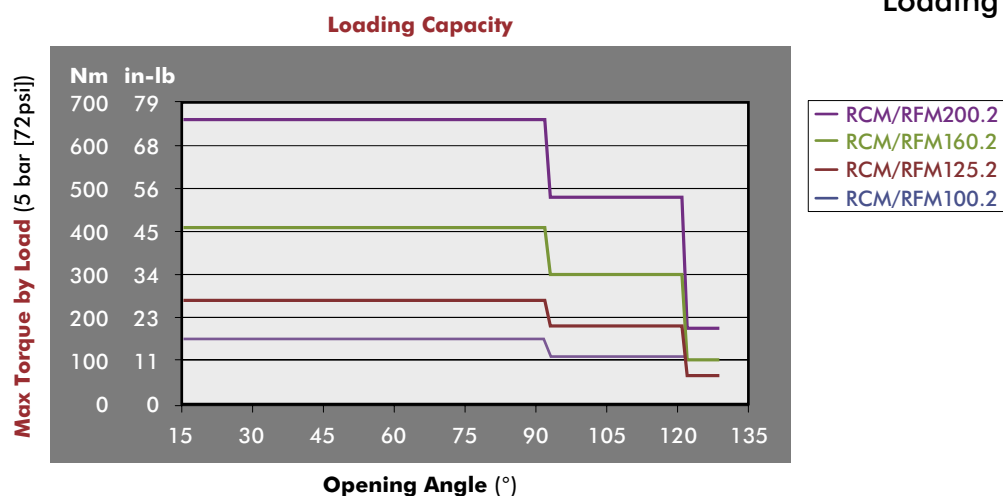
RCM/RFM125, 160, 200 Horizontal "O/LS" Orientation Saddle Dimensions





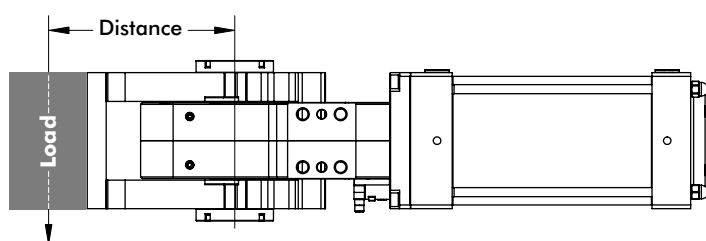
For Models	A	B	C	D	L1	L2	L3	P1-P3
RCM/RFM100.2	[4.53] 115	[4.53] 115	[3.94] 100	[0.75] 19	[25.41] 645,5	[12.76] 324	[0.79] 20	[1/2NPT] G1/2
RCM/RFM125.2	[6.30] 160	[6.30] 160	[4.92] 125	[0.91] 23	[29.17] 741	[14.35] 364,5	[0.94] 24	
RCM/RFM160.2	[7.09] 180	[7.09] 180	[6.30] 160		[29.55] 750,5	[14.59] 370,5	[1.08] 27,5	[3/4NPT] G3/4
RCM/RFM200.2	[8.66] 220	[8.66] 220	[7.87] 200	[0.75] 19	[29.70] 754,5	[14.82] 376,5	[1.16] 29,5	

Loading Capacity



Model	Max. Torque by Load Nm [in-lb]								
	Opening Angle ≤ 92°			Opening Angle > 92° / ≤ 121°			Opening Angle > 121°		
	4 bar [58 psi]	5 bar [72 psi]	6 bar [87 psi]	4 bar [58 psi]	5 bar [72 psi]	6 bar [87 psi]	4 bar [58 psi]	5 bar [72 psi]	6 bar [87 psi]
RCM/RFM100.2	120	150	190	90	110	130	45	55	65
RCM/RFM125.2	180	240	290	140	180	210	55	65	80
RCM/RFM160.2	320	410	500	260	300	360	85	100	125
RCM/RFM200.2	510	660	800	380	480	570	130	175	210

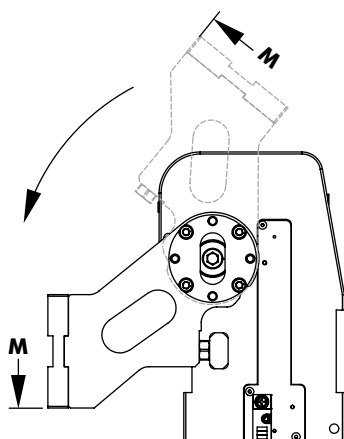
Side Loading Capacity



Max. applicable load with swivel unit positioned on its side (6 bar [87 psi])

Models	Max. Torque by Load @ 6 bar [87 psi] Nm [in-lb]
RCM/RFM100.2	[23] 80
RCM/RFM125.2	
RCM/RFM160.2	[9] 200
RCM/RFM200.2	

Angular Speed Limitation



To avoid elevated angular speed it's necessary to respect the min. times among the electric signal of opening and that of closing brought in tab.

If don't respect the value report in tab, the device may break.

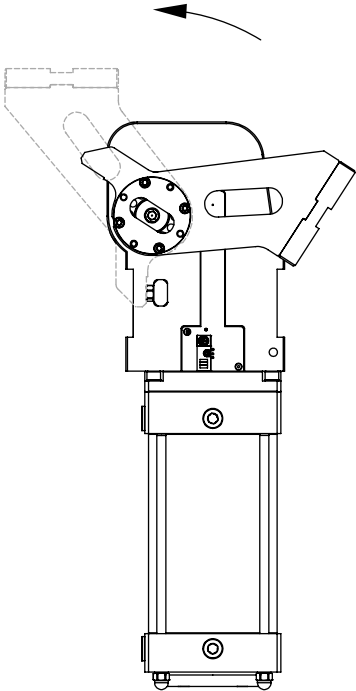
Model	Least Time Between Opening Electric Signal & Closing (Seconds) @ 6 bar [87 psi]				
	45°	76°	91°	121°	129°
RCM/RFM100.2	0.6	0.9	1.0	1.2	1.5
RCM/RFM125.2	0.8	1.1	1.2	1.4	1.7
RCM/RFM160.2	0.9	1.2	1.3	1.5	1.8
RCM/RFM200.2	1.4	1.7	1.8	2.1	2.5

RCM/RFM

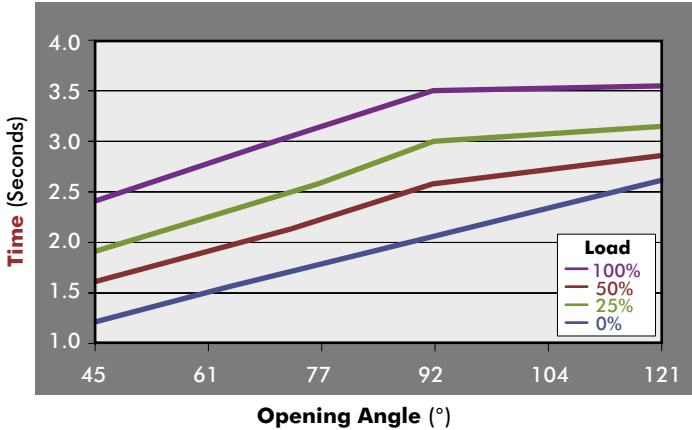
Pneumatic Pivot Units | Time Diagrams

Closing Operation

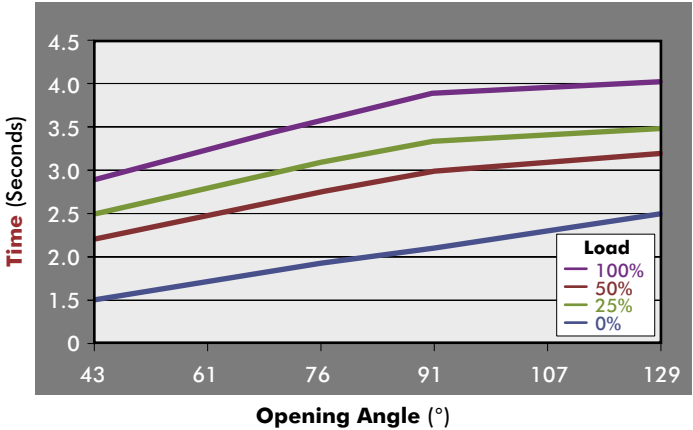
Working Pressure: 5 bar [72 psi]
Arm Type: O (shown)
Swivel Unit Position: Vertical (shown)



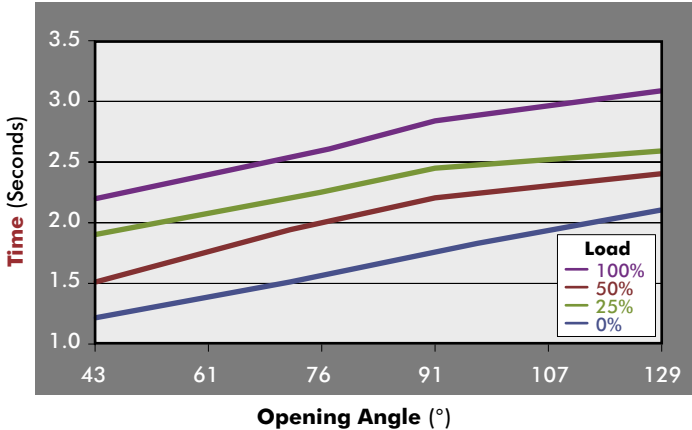
RFM/RCM100.2



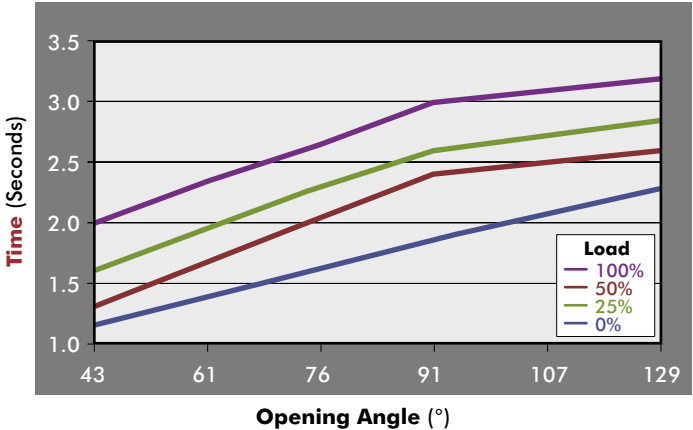
RFM/RCM125.2



RFM/RCM160.2



RFM/RCM200.2

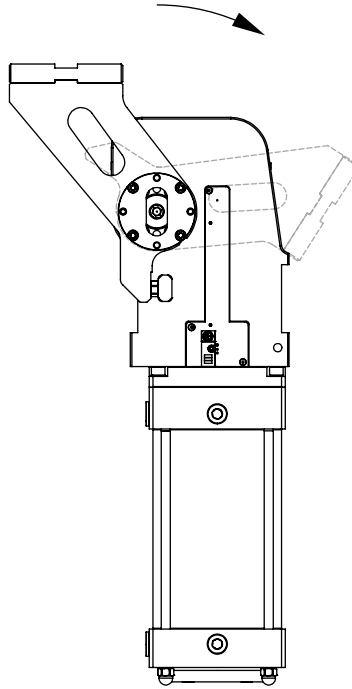


Opening Operation

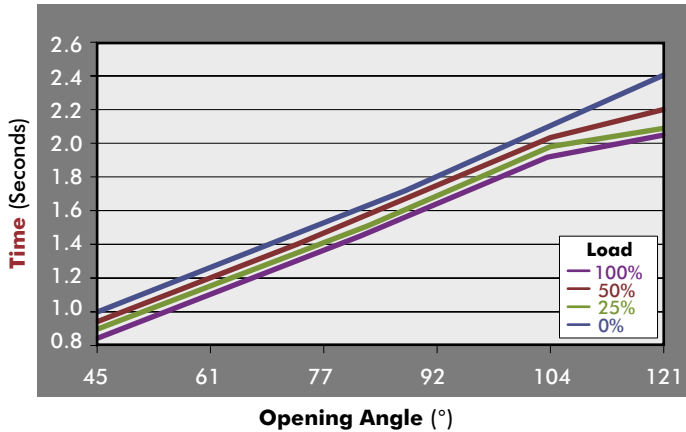
Working Pressure: 5 bar [72 psi]

Arm Type: O (shown)

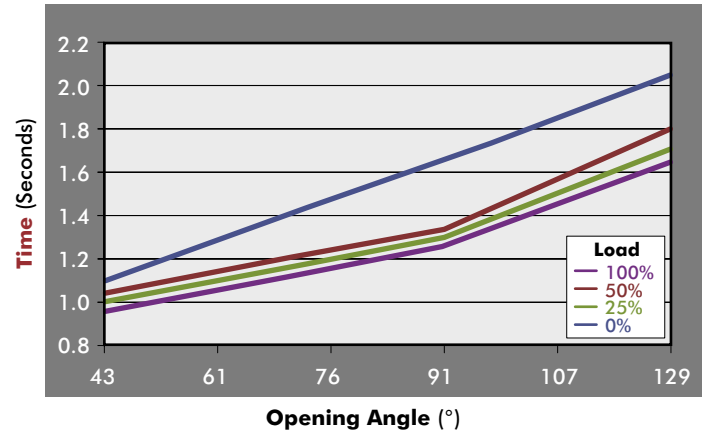
Swivel Unit Position: Vertical (shown)



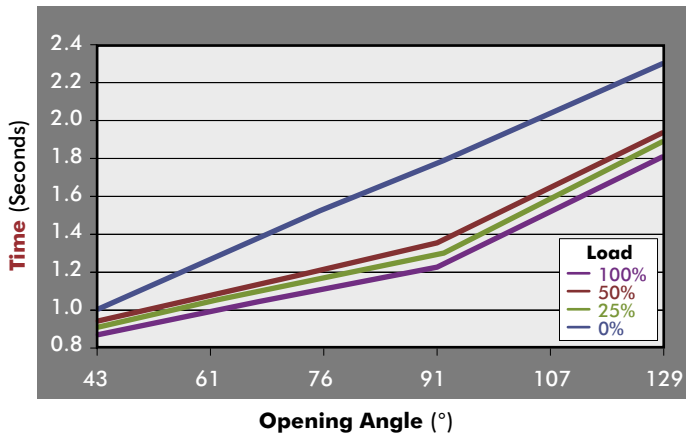
RFM/RCM100.2



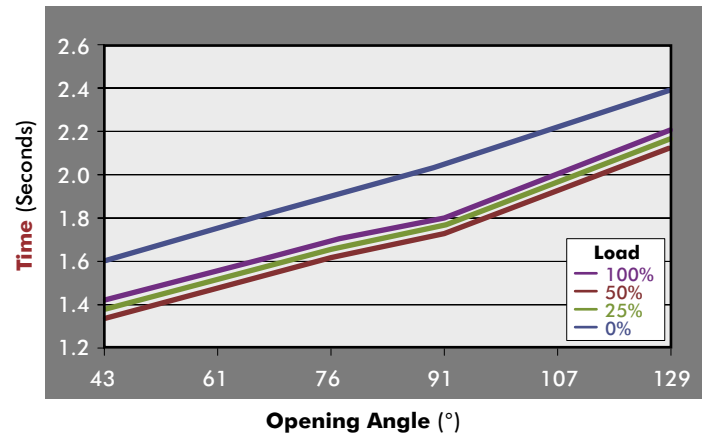
RFM/RCM125.2



RFM/RCM160.2



RFM/RCM200.2



RCM/RFM

Pneumatic Pivot Units | Sensor Technical Specifications

Open/Close Sensor

Proximity Switch Type:	Pepperl+Fuchs or Turck*
Feeding Voltage:	10-30 VDC
Max. Commutating Current:	200 mA
Power Supply:	< 20mA
Voltage Drop:	< 2 V
Temperature Range:	-25° / 70° C

Pepperl+Fuchs

for Model	Power Amplifier (1)	Sensor's Satellite (2)	Complete Inductive Switch
RCM/RFM100.2	3/413	3/417	RFMSI – 1.2/A
RCM/RFM125.2			RFMSI – 125.2/A
RCM/RFM160.2			RFMSI – 160.2/A
RCM/RFM200.2			RFMSI – 200.2/A

Turck

for Model	Sensor	Complete Inductive Switch
RCM/RFM100.2	3/017	RFMSI – 1.2
RCM/RFM125.2	3/383	RFMSI – 125.2
RCM/RFM160.2		RFMSI – 160.2
RCM/RFM200.2		RFMSI – 200.2

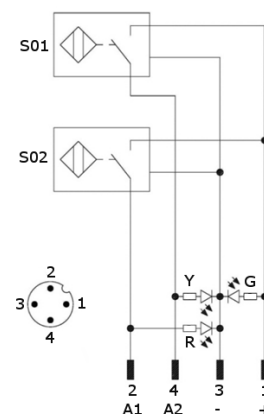


Pepperl+Fuchs



Turck

S01 = Opening Signal
S02 = Closing signal
Y = Yellow LED
G = Green LED
R = Red LED
1 = Brown Wire
2 = Black Wire
3 = Blue Wire
4 = White Wire



Integrated Locking Sensor (SBI)

Locking Sensor Type:	Pepperl+Fuchs† or Turck*
Output Type:	PNP
Feeding Voltage:	10-30 VDC
Max. Commutating Current:	200 mA
Power Supply:	< 25mA
Voltage Drop:	< 2 V
Temperature Range:	-25° / 70° C

Pepperl+Fuchs

for Model	Sensor Type
RFM100.2	RF1 – BIF
RFM125.2	
RFM160.2	RF2 – BIF
RFM200.2	

Turck

for Model	Sensor Type
RFM100.2	RF1T – BIF
RFM125.2	
RFM160.2	RF2T – BIF
RFM200.2	

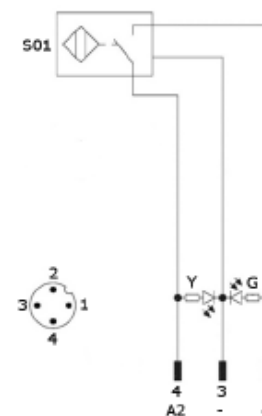


Pepperl+Fuchs



Turck

S01 = Opening Signal
Y = Yellow LED
G = Green LED
1 = Brown Wire
3 = Blue Wire
4 = White Wire



*Proximity switch and locking sensor types cannot be mixed.

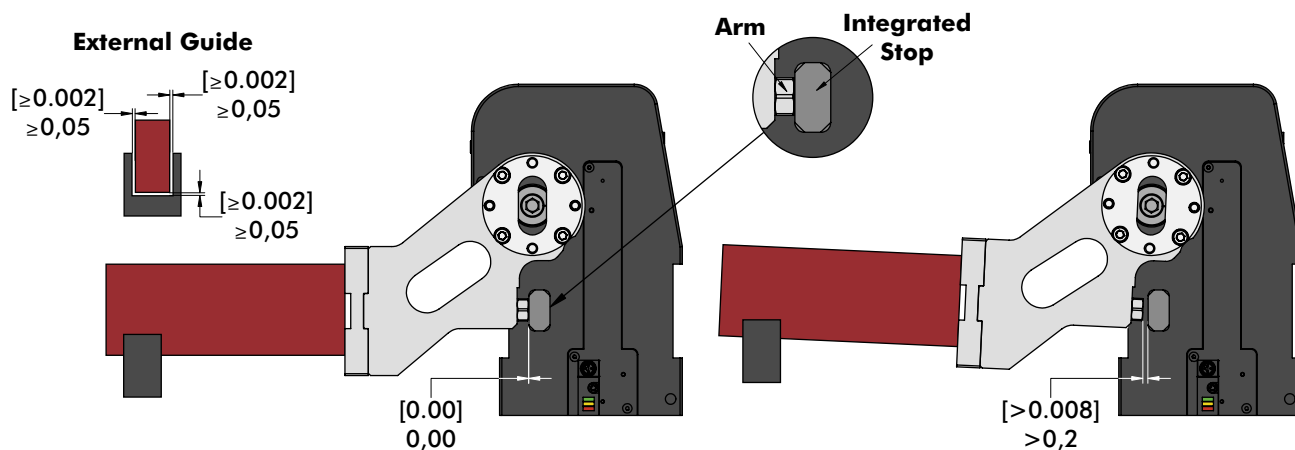
†Pepperl+Fuchs standard unless Turck open/closed proximity sensor is chosen.

Model	Opening Angle (°)	Air consumption @ 5 bar [72 psi] litre [ft3]	Air Consumption @ 6 bar [87 psi] litre [ft3]
RCM/RFM100.2	29°	5,9 [167]	6,9 [195]
	77°	10,3 [292]	12,1 [343]
	121°	14,3 [405]	16,7 [473]
RCM/RFM125.2	15°	7,9 [224]	9,2 [261]
	76°	18,0 [510]	21,0 [595]
	107°	22,4 [634]	26,2 [742]
	129°	24,7 [699]	28,8 [816]
RCM/RFM160.2	15°	14,2 [402]	16,6 [470]
	76°	31,0 [878]	36,2 [1025]
	107°	38,5 [1090]	44,9 [1271]
	129°	42,2 [1195]	49,3 [1396]
RCM/RFM200.2	15°	20,8 [589]	24,3 [688]
	76°	47,4 [1342]	55,3 [1566]
	107°	59,2 [1676]	69,1 [1957]
	129°	65,1 [1843]	76,0 [2152]

Shock Absorber, External Stop Guide Usage

Make sure that the swivel unit makes the complete stroke until the closing position is reached (0°). Any interference with external bodies can cause serious damage to the device and to the equipment mounted on it.

Note: The use of external stops and shock absorbers is not recommended as they can have negative effects on the life of the unit.



CORRECT USE: Integrated Stop is properly used. The distance between the arm and the Integrated Stop = [0.00] 0,00

INCORRECT USE: External Stop being used does not allow the arm to reach a 0° position. The distance between the arm and the Integrated Stop is greater than [0.008] 0,2

If External Guides are used, the following points must be guaranteed:

- The swivel unit must fully reach the closed position
- The above measures for External Guides must be maintained
- They must not be used as External Stops

If the points indicated above are not followed, we reserve the right to void the warranty.